

# Comparing BSDF data from a real and a virtual goniophotometer

**Andreas Noback<sup>+</sup>, Lars O. Grobe\*, Stephen Wittkopf\***

<sup>+</sup>Technische Universität Darmstadt

<sup>\*</sup>Competence Centre Envelopes and Solar Energy (CC-EASE),  
Lucerne University of Applied Science and Arts

15<sup>th</sup> International Radiance Workshop 2016

2016, Padua, Italy

## Outline

- Why would you compare BSDF data from a real and a virtual goniophotometer?
- How to simulate a goniophotometer with Radiance photon mapping?
- How to compare high resolution BSDF data?
- What are the results?
- Outlook

## **Why would you compare BSDF data from a real and a virtual goniophotometer?**

- Approve your models, quantify errors
- Understand the (unexpected) results of your measurements
- Find and quantify differences between design and production samples of optical components

## Scanning goniophotometer PAB Advanced Technologies PG-2

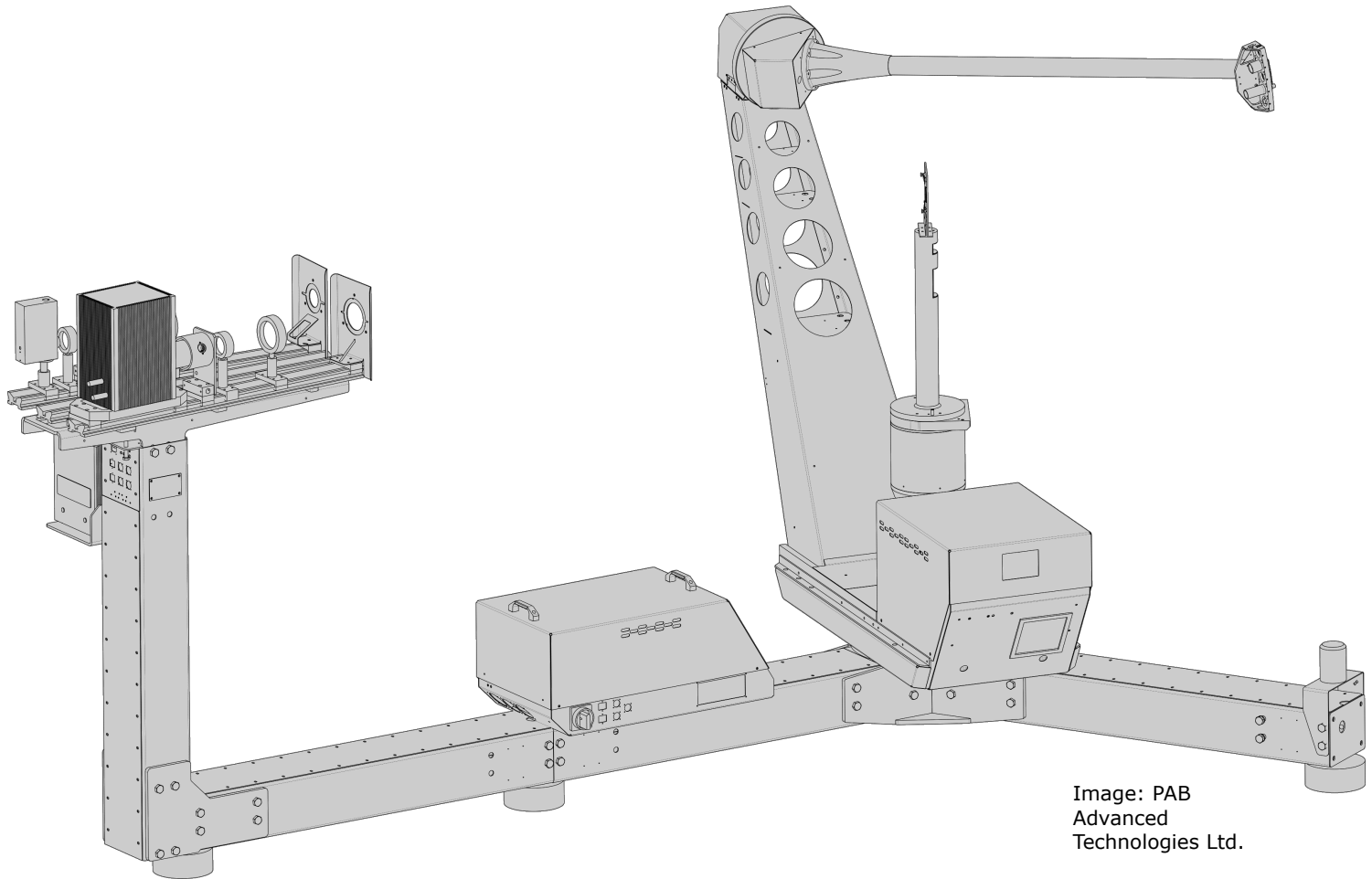


Image: PAB  
Advanced  
Technologies Ltd.



# Implement a virtual goniophotometer with Radiance pmap: Illumination system

```
void light lampMat
0
0
3 100000 100000 100000
```

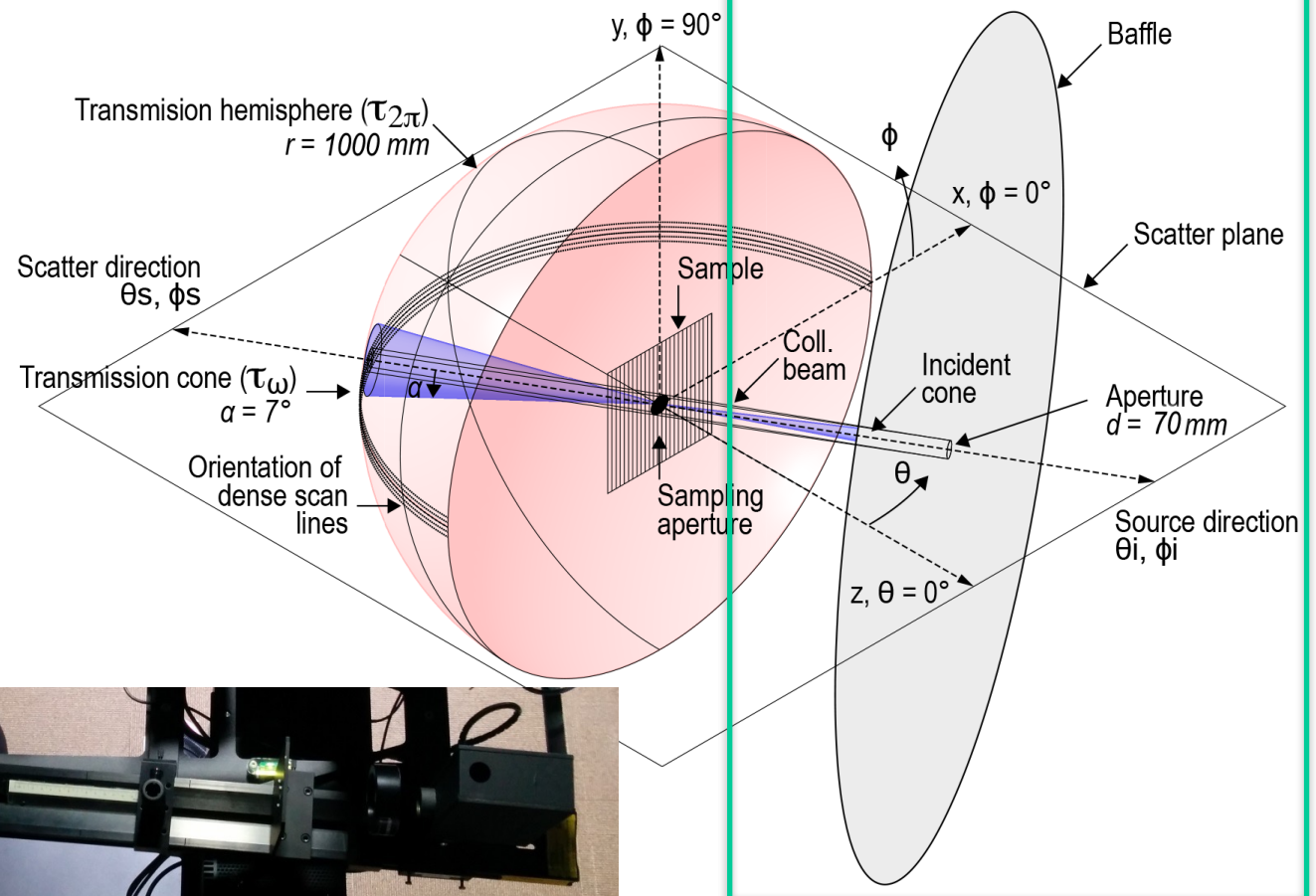
```
lampMat source lampObj
0
0
4 0 0 1 .5
```

```
void plastic baffleMat
0
0
5 0 0 0 0
```

```
baffleMat ring baffleObj
0
0
8 0 0 1.1 0 0 1 0.035 1.5
```

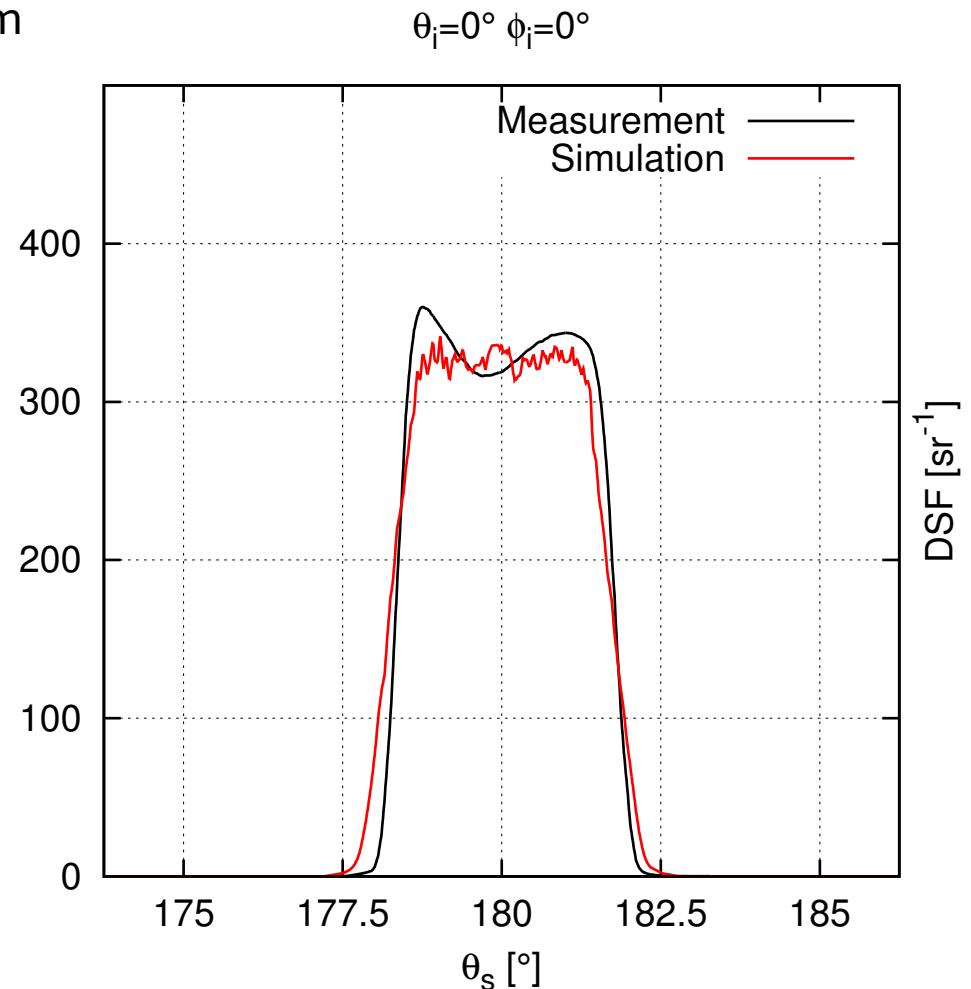
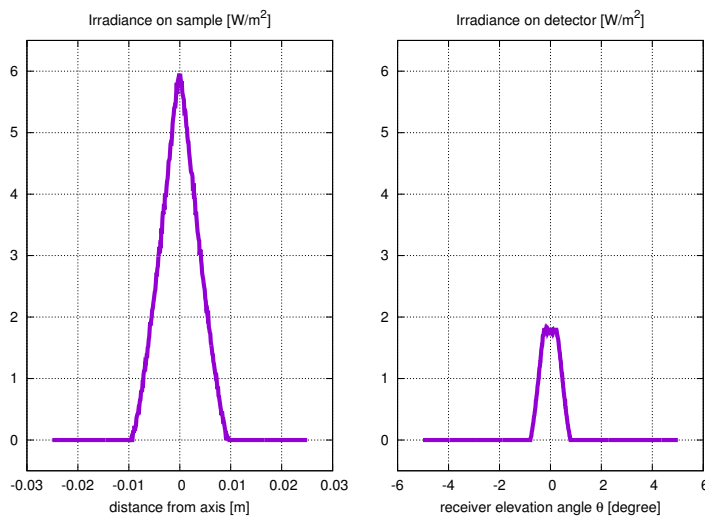
```
void antimatter photonMat
1 void
0
0
```

```
photonMat ring photonObj
0
0
8 0 0 1.1 0 0 -1 0 0.035
```



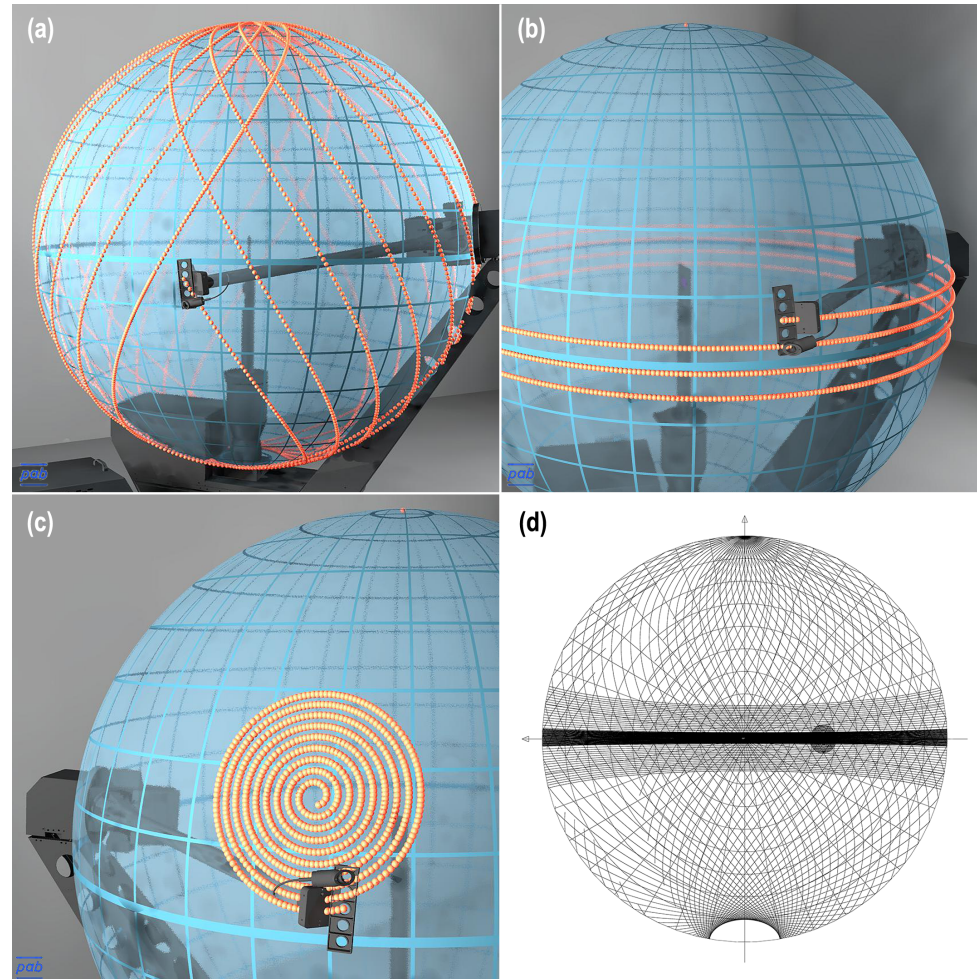
## Implement a virtual goniophotometer: Illumination system

- Works well for a collimated beam
- Edge bias and half shadow is similar to falloff of the illumination system
- Works less good for smaller beams



# Implement a virtual goniophotometer with Radiance map: Sensor positions

```
[header]
#datapoints_in_file    505907
#format: theta        phi          DSF
98.04440  59.79114  1.209e-03
98.04304  59.77517  1.327e-03
98.04214  59.75856  1.782e-03
98.04059  59.74181  9.321e-04
98.03952  59.72591  1.729e-03
98.03831  59.71072  1.432e-03
98.03691  59.69475  1.333e-03
98.03551  59.67878  1.351e-03
98.03429  59.66359  1.541e-03
[...]
```



Images a-c: PAB  
Advanced  
Technologies Ltd.

# Implement a virtual goniophotometer with Radiance pmap: Sensor sphere

```
void antimatter photonMat
```

```
1 void
```

```
0
```

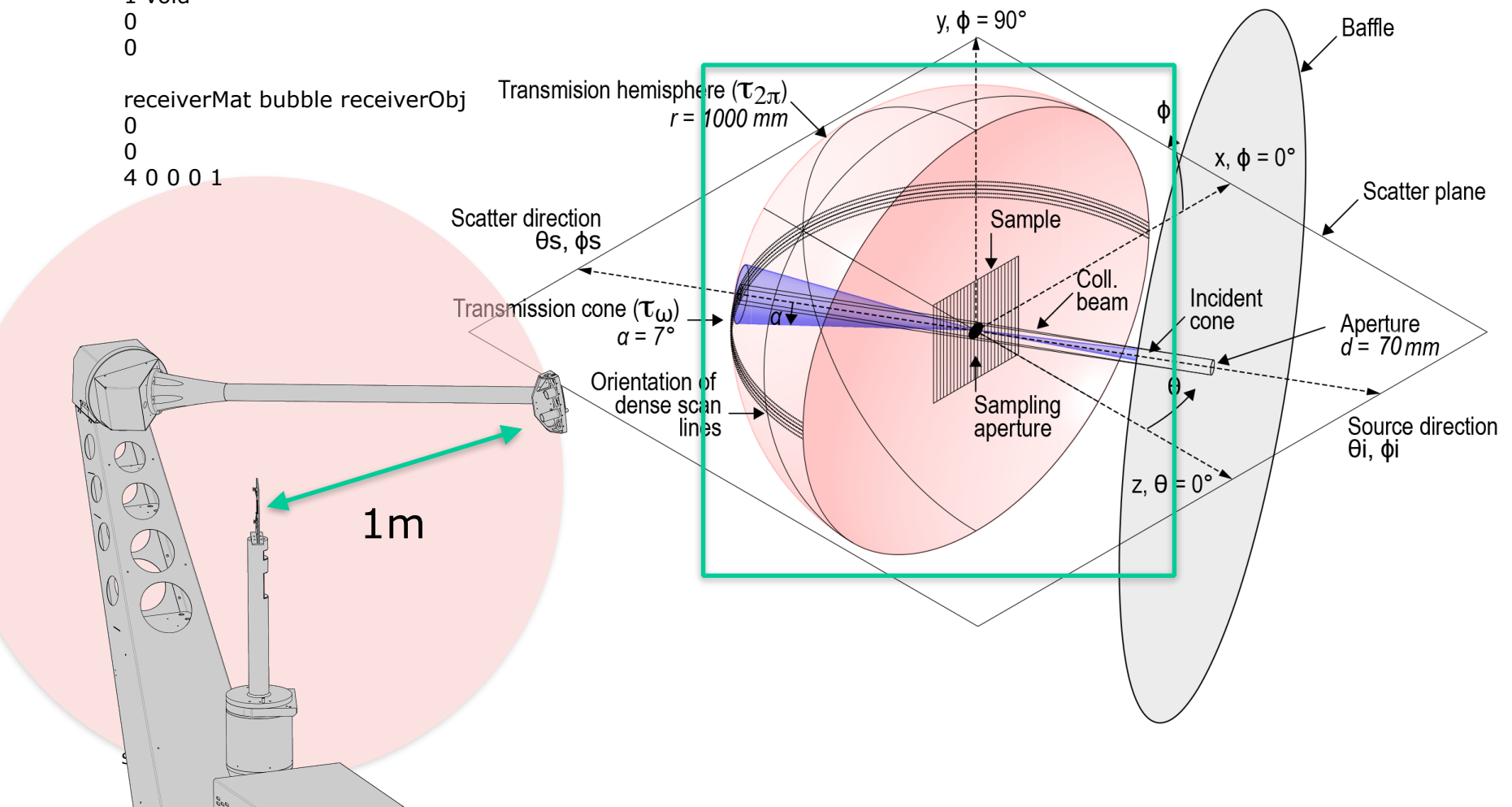
```
0
```

```
receiverMat bubble receiverObj
```

```
0
```

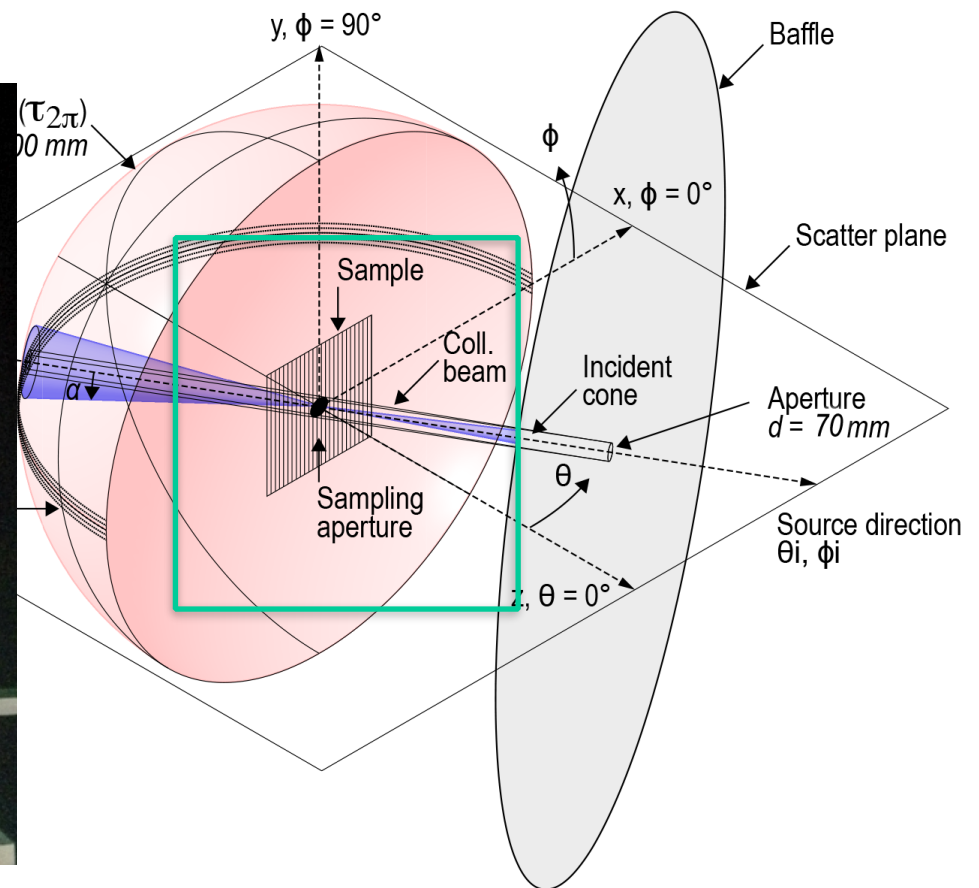
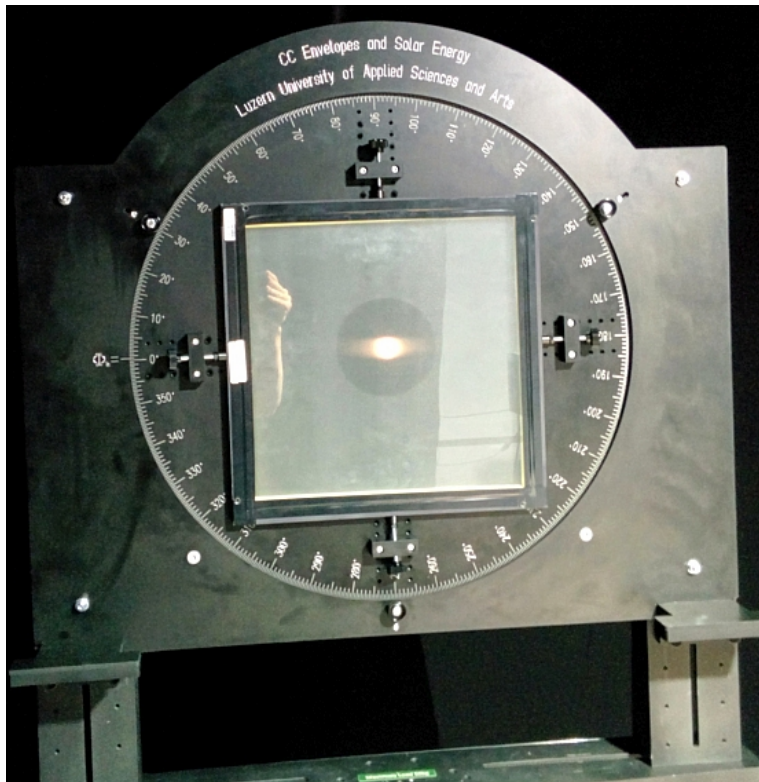
```
0
```

```
4 0 0 0 1
```



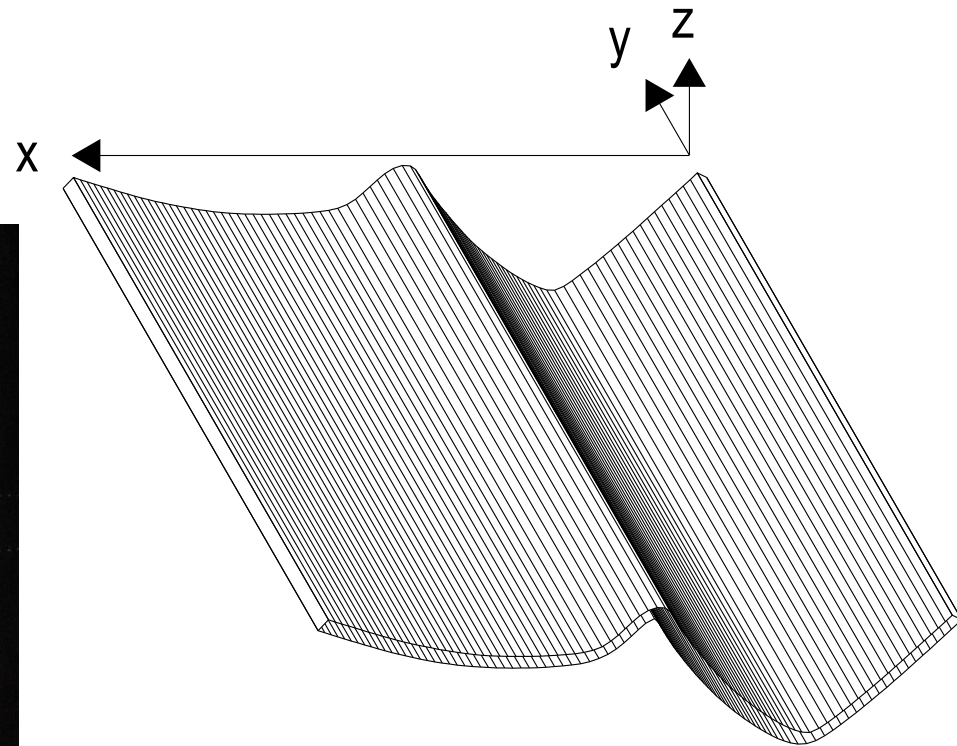
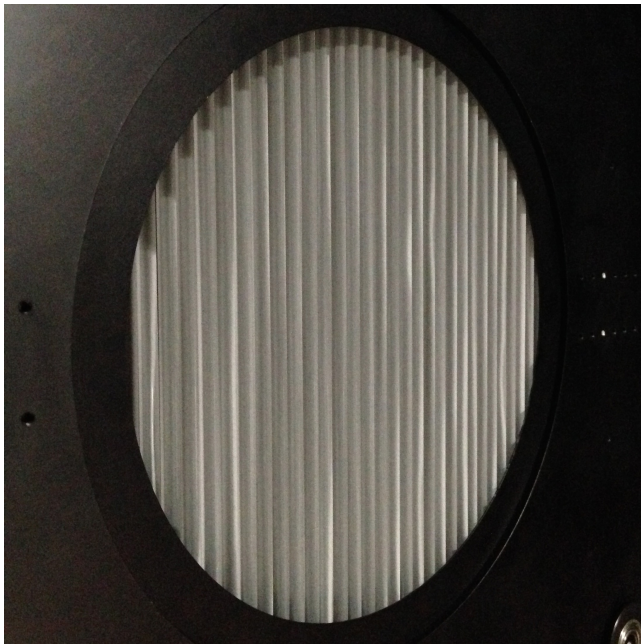
# Implement a virtual goniophotometer with Radiance pmap: Sample

xform -ry \$thetain -rz \$phiin



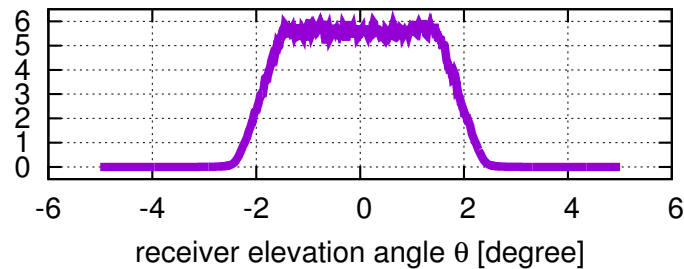


# Implement a virtual goniophotometer with Radiance pmap: Sample

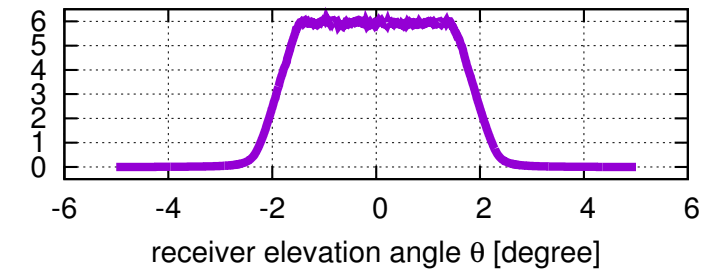


## Implement a virtual goniophotometer with Radiance pmap: mkpmap and rtrace

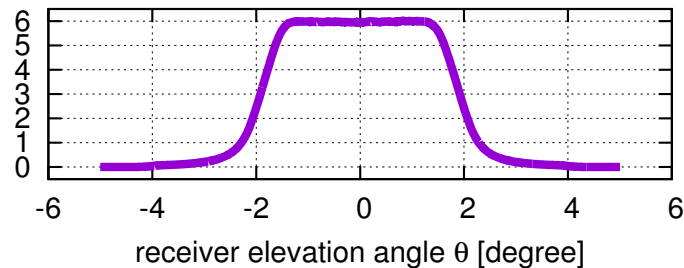
Bandwidth 1K photons: Irradiance on detector [ $\text{W/m}^2$ ]



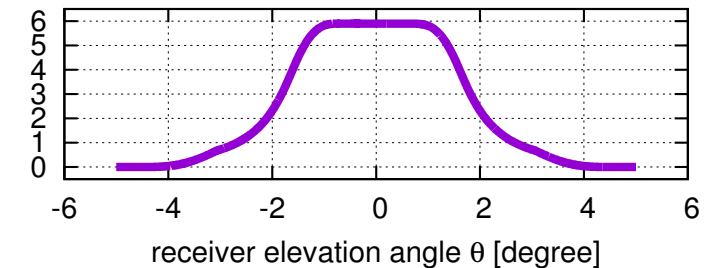
Bandwidth 10K photons: Irradiance on detector [ $\text{W/m}^2$ ]



Bandwidth 100K photons: Irradiance on detector [ $\text{W/m}^2$ ]



Bandwidth 1M photons: Irradiance on detector [ $\text{W/m}^2$ ]



`mkpmap -apo photonMat -aps receiverMat -apg sample.gpm 8000000 sample.oct`

`rtrace $rtrace_opts -ap 2000 -ab -1 sample.oct`

## Implement a virtual goniophotometer with Radiance pmap: mkpmap and rtrace

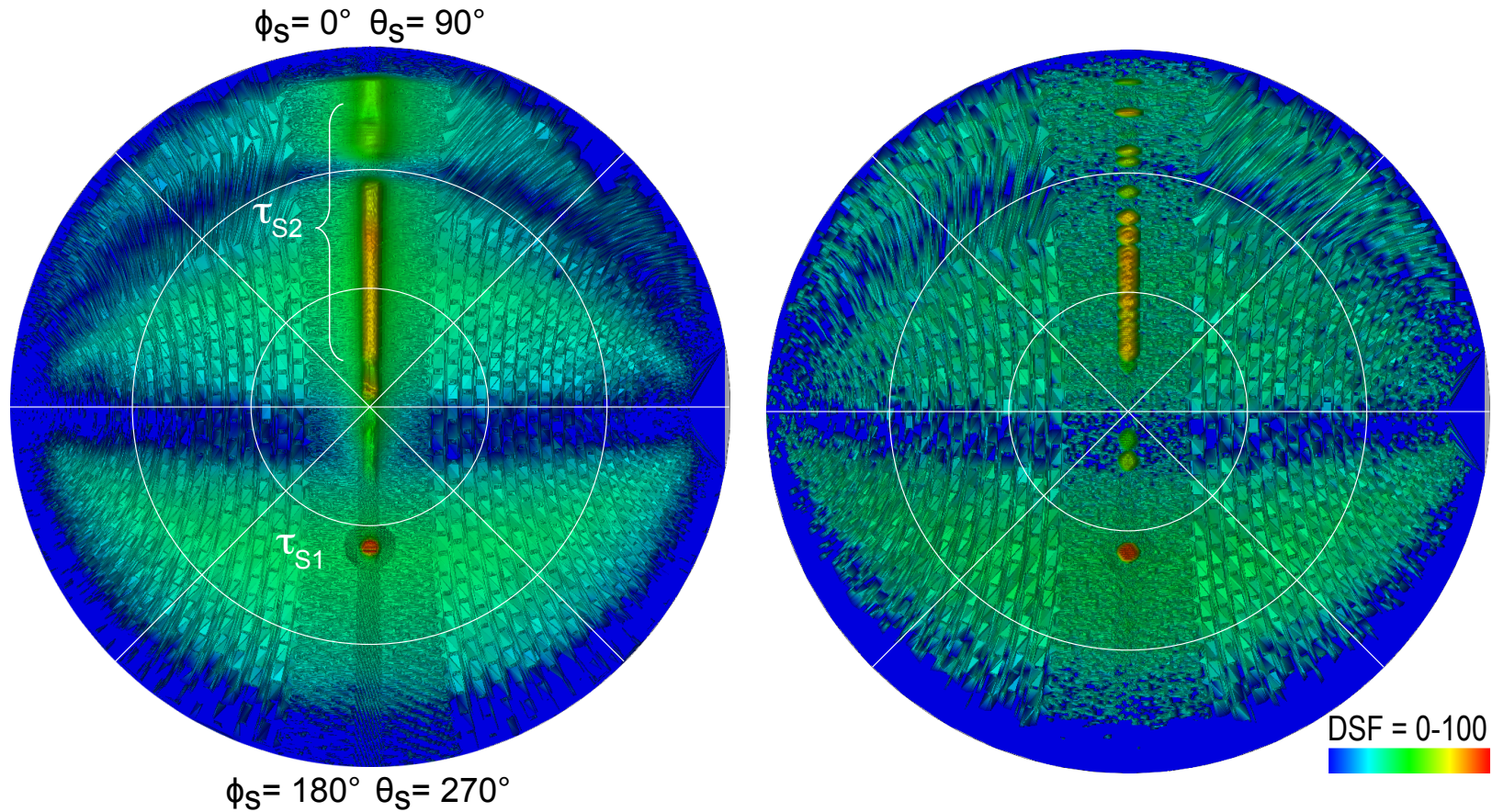
```
cat input_vectors.dat | \  
rcalc -e '$1=$1; $2=$2; $3=$3; $4=-.1*$1; $5=-.1*$2; $6=-.1*$3' | \  
rtrace $rtrace_opts $pmapstring sample.oct > $out.dat
```

input\_vector.dat = output pg2

```
[header]  
#datapoints_in_file 505907  
#format: theta      phi      DSF  
98.04440 59.79114 1.209e-03  
98.04304 59.77517 1.327e-03  
98.04214 59.75856 1.782e-03  
98.04059 59.74181 9.321e-04  
98.03952 59.72591 1.729e-03  
98.03831 59.71072 1.432e-03  
98.03691 59.69475 1.333e-03  
[...]
```



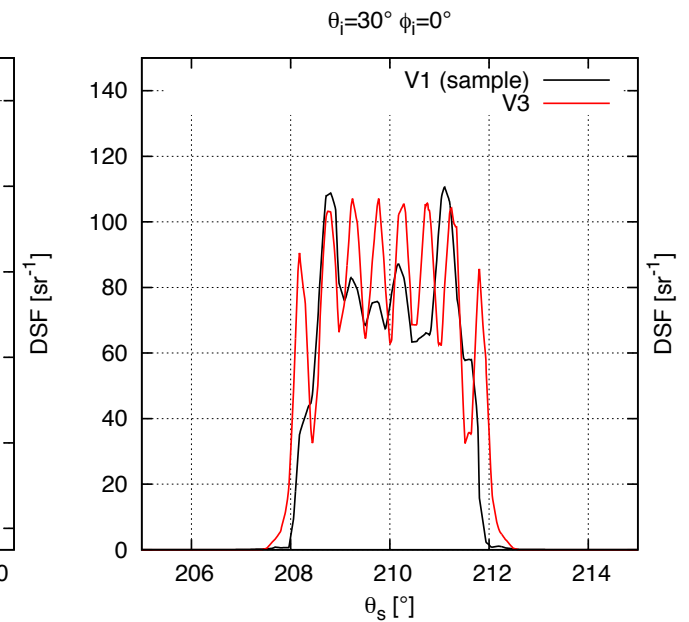
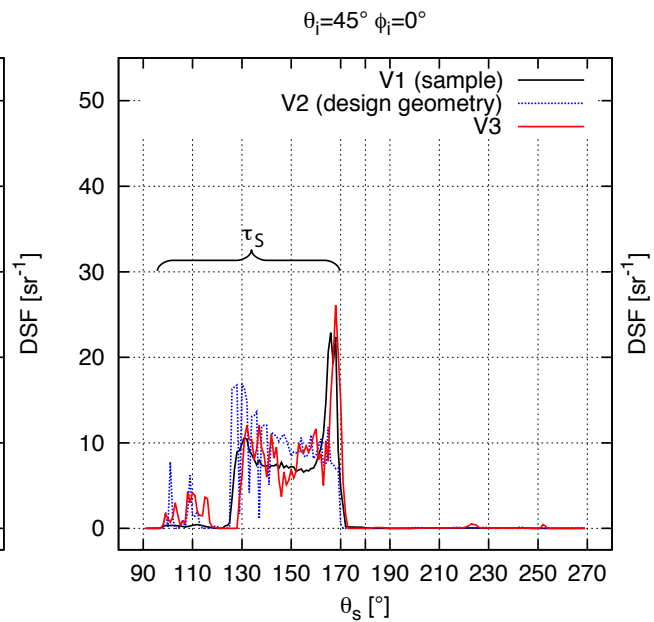
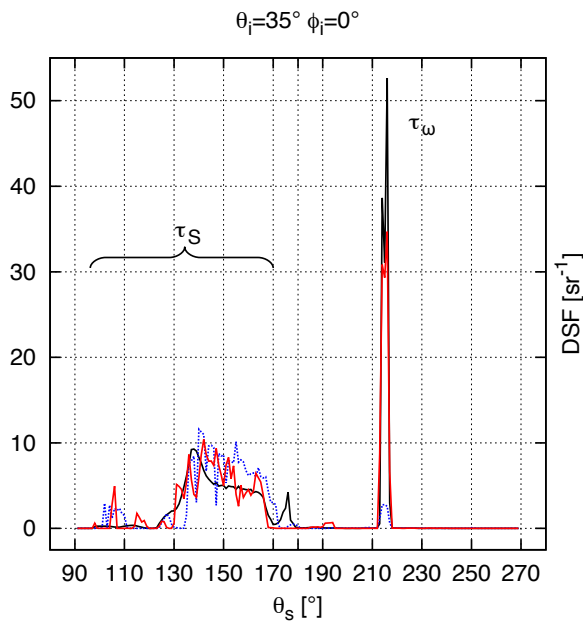
# Implement a virtual goniophotometer with Radiance pmap: Results



DSF Measurement  $\theta_i = 35^\circ$

DSF Simulation  $\theta_i = 35^\circ$

# Implement a virtual goniophotometer with Radiance pmap: Results



## How to compare high resolution BSDF data: Global and local accordance

Global accordance

$$f_{A,B} = 100 \left( 1 - \sqrt{\frac{\sum_{j=1}^n (DSF_{A,j} - DSF_{B,j})^2}{\sum_{j=1}^n (DSF_{A,j} + DSF_{B,j})^2}} \right)$$

Local accordance

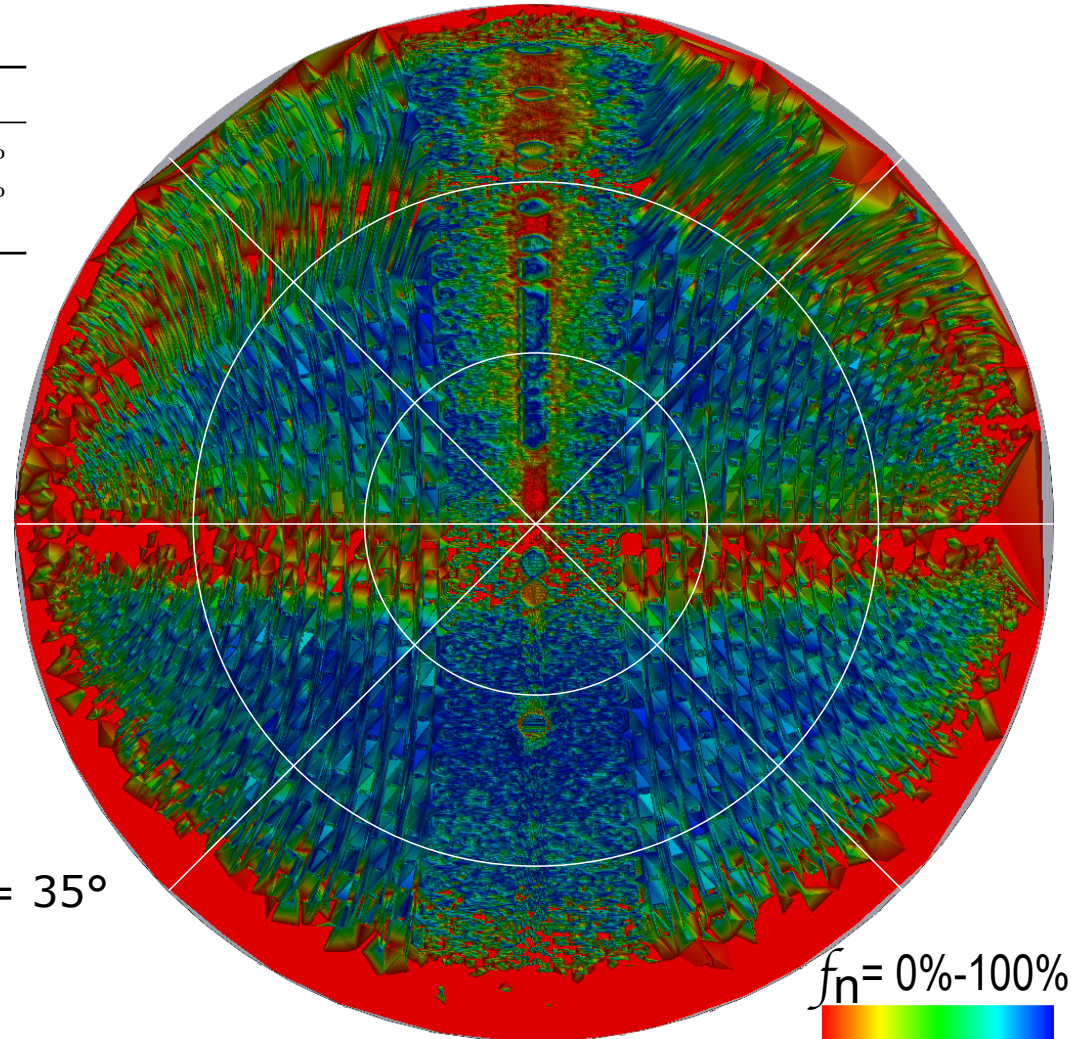
$$f_{j,A,B} = 100 \left( 1 - \left| \frac{DSF_{A,j} - DSF_{B,j}}{DSF_{A,j} + DSF_{B,j}} \right| \right)$$

## How to compare high resolution BSDF data: Global and local accordance

$\theta_i$	0°	30°	35°	40°	45°	50°
$f_{V2,V1}$	–	75%	20%	68%	65%	66%
$f_{V3,V1}$	–	84%	74%	70%	71%	74%
$f_{RB}$	92%	–	–	–	–	–

Global accordance

Local accordance  $\theta_i = 35^\circ$



# Compare high resolution BSDF data: More Results



Article

## Accordance of Light Scattering from Design and De-Facto Variants of a Daylight Redirecting Component

Andreas Noback <sup>1,2</sup>, Lars O. Grobe <sup>1,\*</sup> and Stephen Wittkopf <sup>1</sup>

<sup>1</sup> Competence Center Envelopes and Solar Energy, Lucerne University of Applied Sciences and Arts, 6048 Horw, Switzerland; mail@noback.info (A.N.); stephen.wittkopf@hslu.ch (S.W.)

<sup>2</sup> Faculty of Architecture, Technische Universität Darmstadt, 64287 Darmstadt, Germany

\* Correspondence: larsoliver.grobe@hslu.ch; Tel.: +41-41-349-3632

Academic Editor: Yuehong Su

Received: 3 June 2016; Accepted: 12 August 2016; Published: 18 August 2016

**Abstract:** For the systematic development of a small-scale daylight-redirecting louver system the impact of manufacturing on light scattering characteristics has to be quantified, localized and understood. In this research, the accordance of the measured scattering distributions of a de-facto production sample *V1* with the computed predictions based on its design geometry *V2* are quantified for selected incident light directions. A metric describing the global accordance of distributions is adapted to quantify their overall difference. A novel metric of local accordance allows further analysis. A particular low global accordance between *V1* and *V2* is found for an incident elevation  $\theta_i = 35^\circ$ . To test the hypothesis that this result can be explained by observed geometric deviations, a simulation model *V3* replicating these is compared to the design. The hypothesis is supported by the resulting high degree of accordance. The low local accordance for individual outgoing light directions indicates geometric non-uniformity of the sample *V1*. This method has been found useful for product development and quality assurance. Beyond their application in the proposed method, global and local accordance have potential applications in all fields of light scattering measurements.

**Keywords:** daylight redirection; BSDF; light scattering; simulation; goniophotometry; manufacturing deviation; quality assurance

## Outlook

- How important are deviations from production for daylight autonomy or glare?
- Are there alternate metrics?
- How to compare data with deviating resolution?
- What is the relation of angular resolution and components size?
- Further Applications?
- How to get reliable BSDF for DRCs: repeat measurements, change sample size, measure multiple samples?
- Model the condenser system and optical bench of PG-2: would allow smaller beams and focus points.
- Suggestions?

# Thank you for your attention!

This research was supported by the Swiss National Science Foundation as part of the project "Simulation-based assessment of daylight redirecting components for energy savings in office buildings" (#147053).

[andreas.noback@architektur.tu-darmstadt.de](mailto:andreas.noback@architektur.tu-darmstadt.de)